

Structure and scaling of extreme events in hydrodynamic turbulence

Alain Pumir

Laboratoire de Physique, ENS Lyon, France

and

Max-Planck Institute for Dynamics and Self-Organization, Göttingen, Germany

Joint project with:

Dhawal Buaria, NYU (USA)

Eberhard Bodenschatz (MPI, Göttingen),

PK Yeung (Georgia Tech).

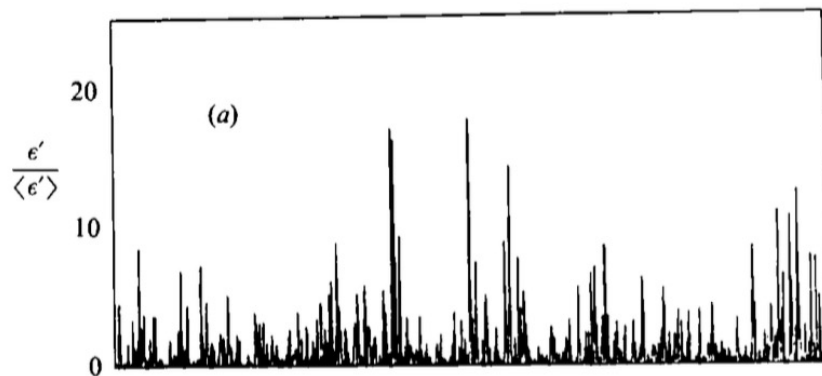


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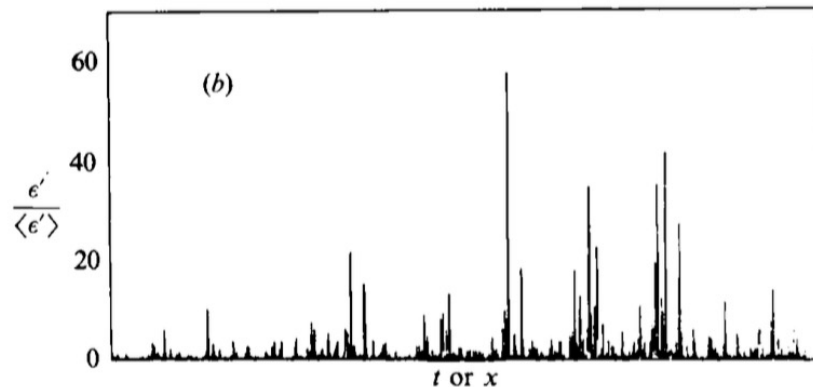
Turbulence and intermittency

- Turbulent flows are known to generate very **large velocity gradients**, the more so as the Reynolds number increases.



(a) Laboratory experiment;
low Reynolds; $R_\lambda \sim 100$.

(b) Atmospheric boundary layer;
high Reynolds; $R_\lambda \sim 1500$.



Phenomenon known as **Intermittency**
(see e.g. Batchelor and Townsend, 1949).

Meneveau and Sreenivasan (1991)

Large velocity gradients in turbulent flows: how large ?

ε = kinetic energy dissipation is independent in the zero viscosity limit $\nu \rightarrow 0$
[empirical fact; aka “the dissipative anomaly”]

$$\Rightarrow \nu \langle (\partial u)^2 \rangle \sim \varepsilon \sim (U^3/L)$$

The variance of the velocity gradient increases as a function of the Reynolds number:

$$\langle (\partial u)^2 \rangle \propto (\varepsilon/\nu) \simeq (U/L)^2 Re$$

- In addition, the largest values of the gradient grow with Re *much faster* than their mean values *[intermittency]*.

Very large velocity gradients could be generated in the bulk, away from boundaries.

Gradient amplification ?

Vortex stretching

... a very important ingredient in turbulent flows (cf. Tennekes and Lumley) !!!

Equation for the vorticity:

$$\partial_t \omega(\mathbf{x}, t) + (\mathbf{u} \cdot \nabla) \omega = (\omega \cdot \nabla) \mathbf{u} + \nu \nabla^2 \omega(\mathbf{x}, t)$$

How much stretching can the term: $(\omega \cdot \nabla) \mathbf{u}_a \equiv \omega_b S_{ba}$ (S strain-rate tensor) produce?

Dimensionally, S and ω are both velocity gradients. Superficially,

$$d\omega/dt = S \cdot \omega \sim \omega^2$$

Solution: $\omega(t) = \omega(0) / (1 - \omega(0)t) \dots$ blows up at $t^* = 1/\omega(0)$

~ Naïve expectation: $|\omega| \sim |\partial v| \sim 1/(t^* - t)$

Homogeneous isotropic turbulence

Isotropy: fluctuations are invariant under any rotation – invariance under $SO(3)$.

Homogeneity: the flow properties do not vary in space.

- Conceptually simplest setup to study turbulence. Introduced by Taylor (1936), further development by von Karman-Howarth (1938), Kolmogorov (1941), etc etc.
- In practice, flows are stirred in a very anisotropic manner. However, due to turbulence, the flow develops a wide range of length scales, and at the smallest scales, one postulates (expects, etc) that isotropy is restored.
- Convenient to simulate numerically via [*direct numerical simulations \(DNS\)*](#) of the Navier-Stokes equations.

DNS of turbulent flows:
Constraints on intermittency studies

Issues with any intermittency studies

Large velocity gradient \sim *(large velocity difference)/(small distance)*
 \sim *1/(small time)*

=> make sure that spatial resolution is good enough

=> ensure proper time resolution

=> Existence of rare events: statistical convergence is an issue.

In this work: use direct numerical simulations (DNS) of the Navier-Stokes equations at very high resolution, based on pseudo-spectral methods.

Studying the velocity gradient tensor: spatial resolution issues

- *How much can one trust the information concerning large velocity gradients from a limited spatial resolution ?*

The usual resolution criterion for DNS using spectral methods involves :

- the smallest length scale in the flow, the Kolmogorov scale: $\eta = (v^3/\varepsilon)^{1/4}$
- the highest wavenumber resolved: $k_{max} \approx (\sqrt{2/3}) N$, where N is the total number of Fourier modes in any spatial direction.

An accepted criterion for a good simulation :

$$k_{max} \eta \approx 1.5 - 2$$

In terms of the smallest length resolved:

$$\Delta x / \eta [\approx 3 / (k_{max} \eta)] \approx 2 - 1.5$$

Studying the velocity gradient tensor: temporal resolution issues

- Spectral calculations are limited by a Courant-Friedrich-Lewy condition:

$$\Delta t \lesssim \Delta x / |u|$$

The mesh size $\Delta x \sim \eta \sim L R_\lambda^{-3/2}$, so $\Delta t < (L/U) R_\lambda^{-3/2}$.

=> the time step chosen is therefore much smaller than $\tau_K \sim (L/U) R_\lambda^{-1}$, which is the time scale associated with the rms of the velocity gradients.

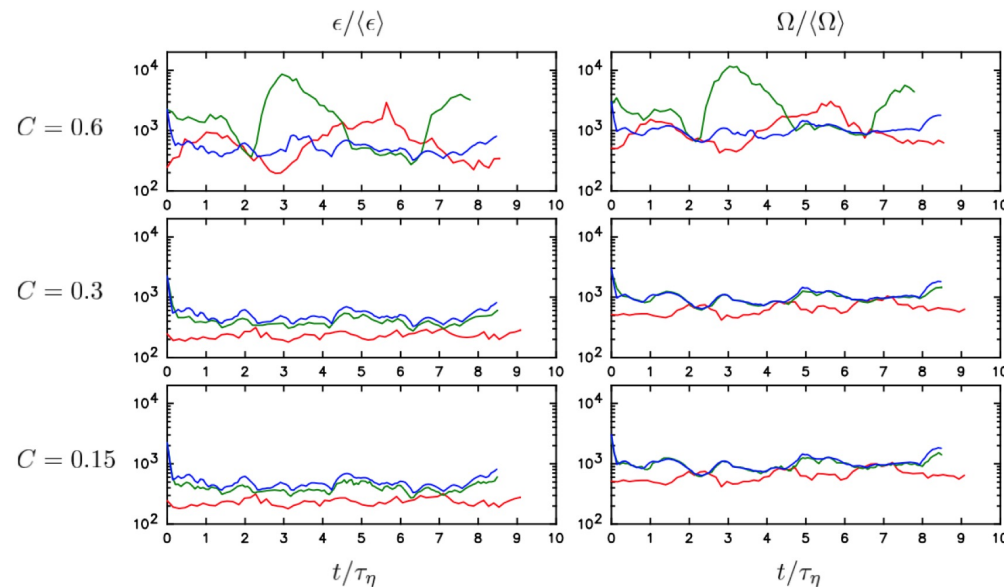
... however ...

Studying the velocity gradient tensor: temporal resolution issues

BUT !!! Velocity gradients MUCH larger than $1/\tau_K$ appear in the flow.

Define: $\Delta t = C \Delta x/|u|_{max}$; $C = \text{Courant \#}$

=> Stability of the integration algorithm ($C \lesssim 1$) isn't good enough; taking too large a time step may lead to spurious results (Yeung, Pope and Sreenivasan, 2018).



Max values of ϵ and $\Omega (\equiv |\omega|^2)$ as a function of time

$$R_\lambda = 390$$

$k_{max} \eta = 1.4$ (red)
 $= 2.8$ (green)
 $= 5.6$ (blue)

Resolution in our study

- Here, use: *Courant # = 0.3*

$k_{max} \eta$ larger than 3; or equivalently: $\Delta x/\eta$ smaller than ~ 1

nb: most runs in fact at $k_{max} \eta \approx 6$. ($\Delta x/\eta \sim 0.5$)

Use a spectral code (Rogallo 1981) with up to 12288^3 modes/colocation points (a few time steps with 18432^3 modes).

R_λ	N^3	$k_{max}\eta$	T_E/τ_K	T_{sim}	N_s
140	1024^3	5.82	16.0	$6.5T_E$	24
240	2048^3	5.70	30.3	$6.0T_E$	24
390	4096^3	5.81	48.4	$2.8T_E$	35
650	8192^3	5.65	74.4	$2.0T_E$	40
1300	12288^3	2.95	147.4	$20\tau_K$	18

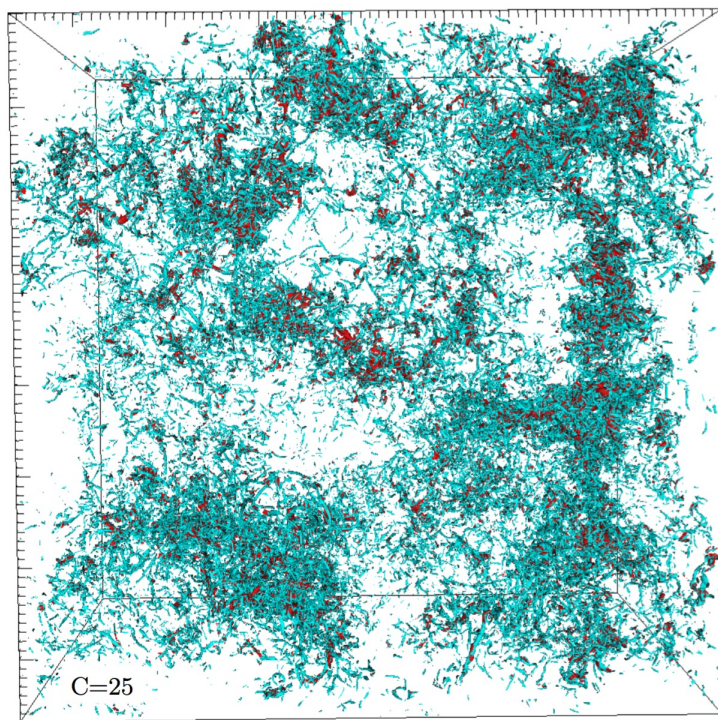
nb: N_s = # of fields considered to construct the statistics.

Intermittency in DNS of turbulent flows

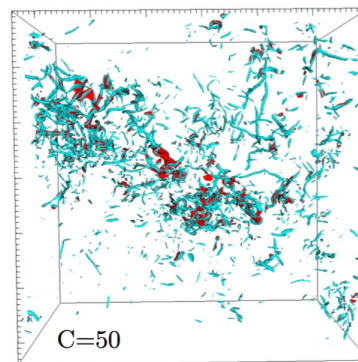
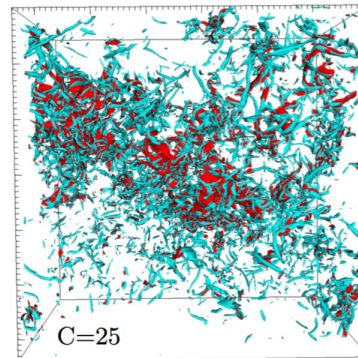
*Structure of the regions of intense
strain/vorticity*

Spatial structure of strain and vorticity

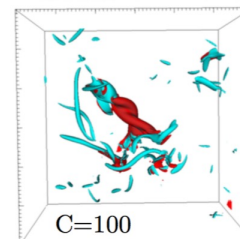
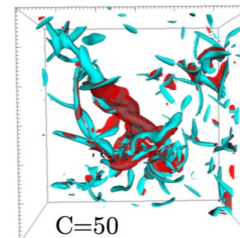
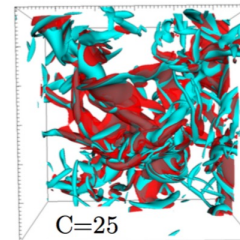
The largest velocity gradient structures are vortex tubes (as found many times before, e.g. Siggia, 1981 (...) Ishihara et al, 2007, 2009).



(a) $(2000\eta)^3$



(b) $(600\eta)^3$



(c) $(150\eta)^3$

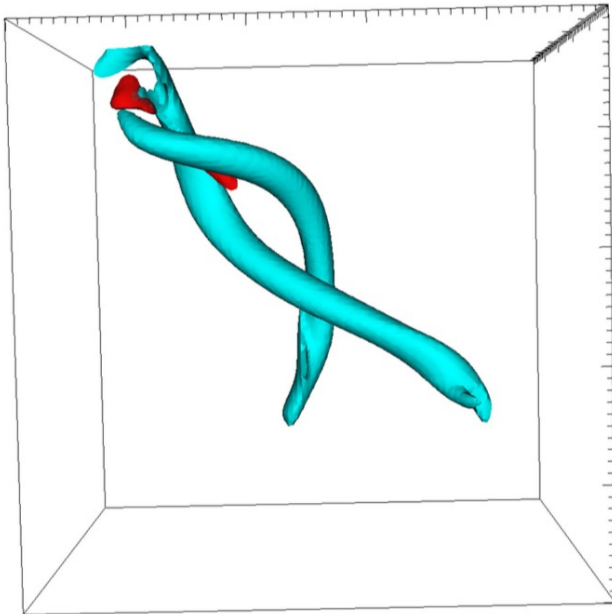
➤ Strain (red) is comparatively much smaller than vorticity (cyan).

➤ The most intense regions of strain and vorticity are not co-located.

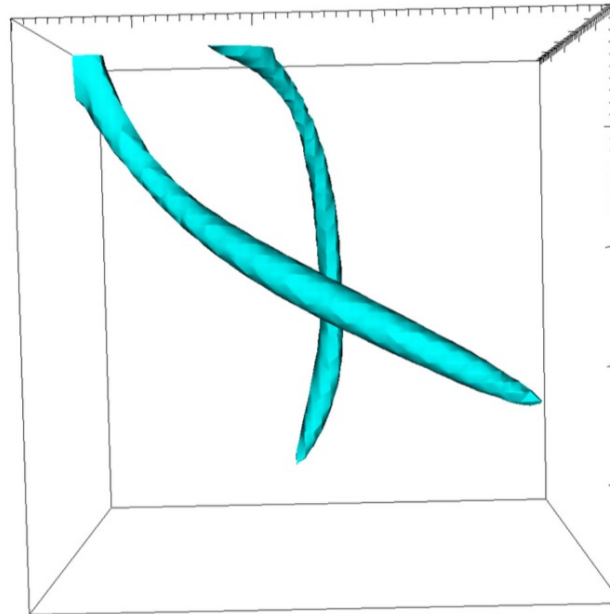
Buaria et al, NJP 2019

Structure of strain and vorticity

- The most intense events are vortex tubes; possibly in weak interaction.



(c) $(50\eta)^3$; $C=500$

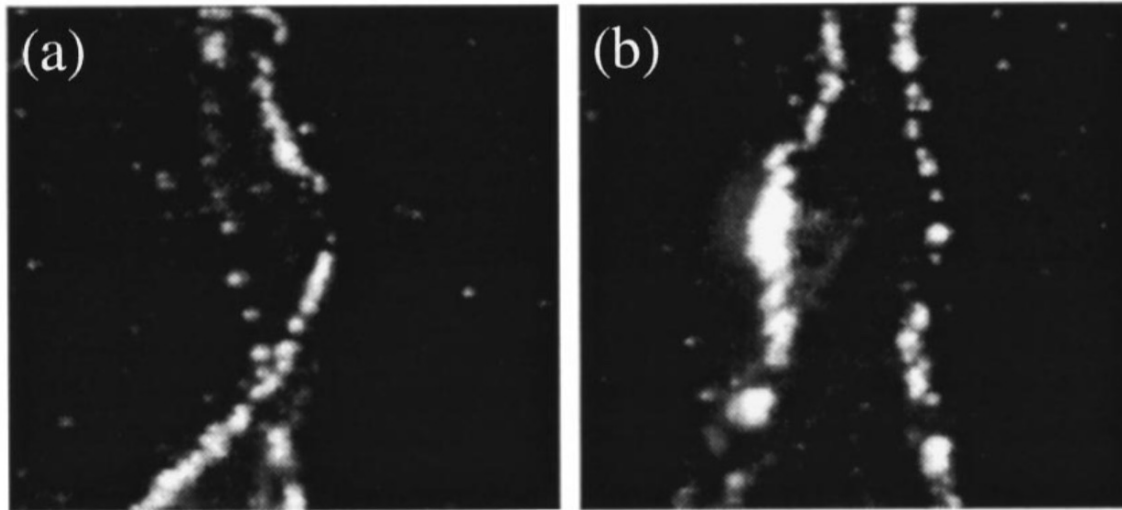


(d) $(25\eta)^3$; $C=1500$

Blown-up view of the most intense velocity gradient region.

Buaria et al, NJP 2019

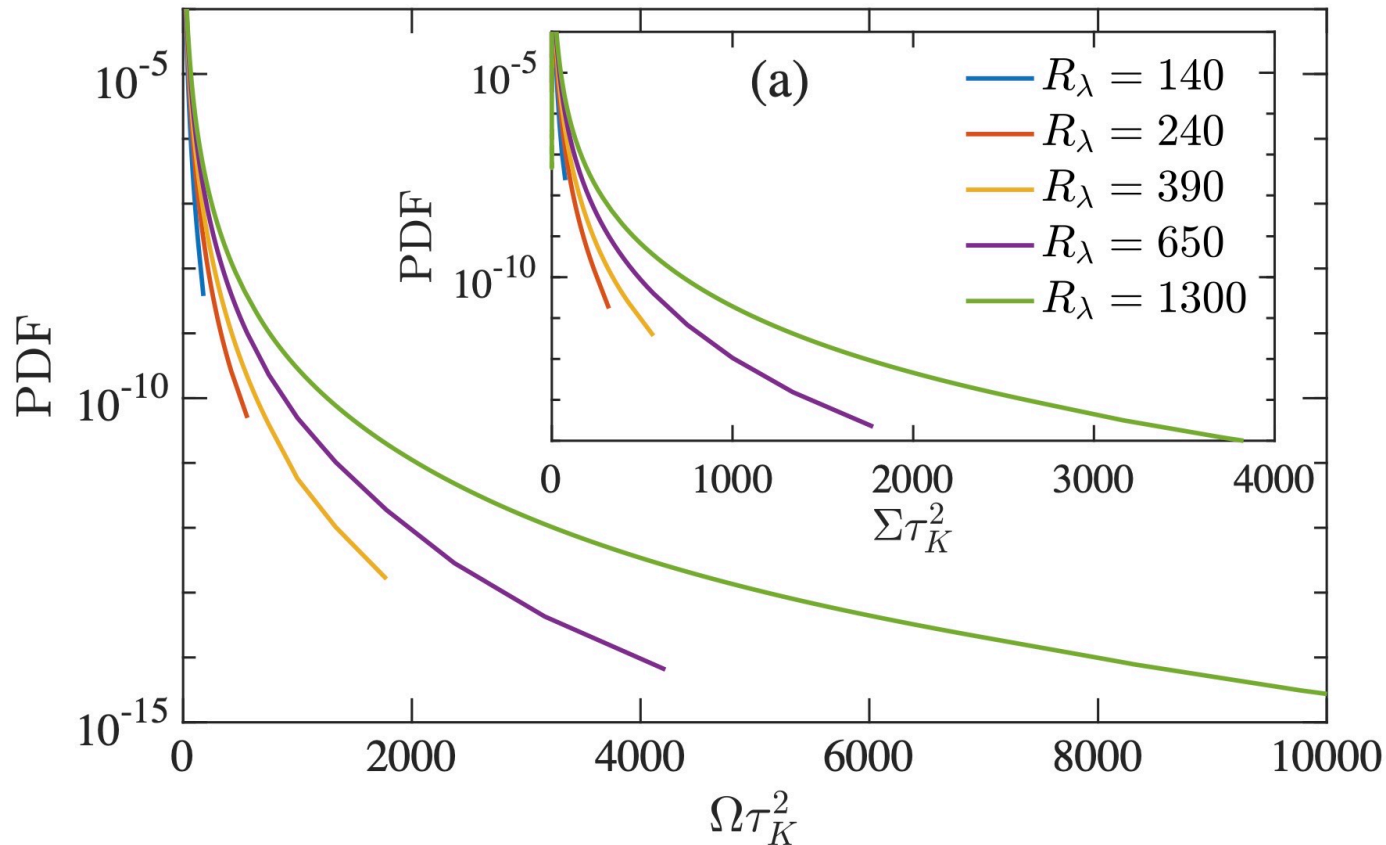
Vortex tubes: not just "in-silico"



LaPorta et al, PoF 2000

- *Visualization of the vortices with cavitation bubbles (see also Douady et al, PRL 1991 etc).*

PDF of $\Omega = \omega^2$ and $\Sigma = 2 \text{tr}(\Sigma^2)$



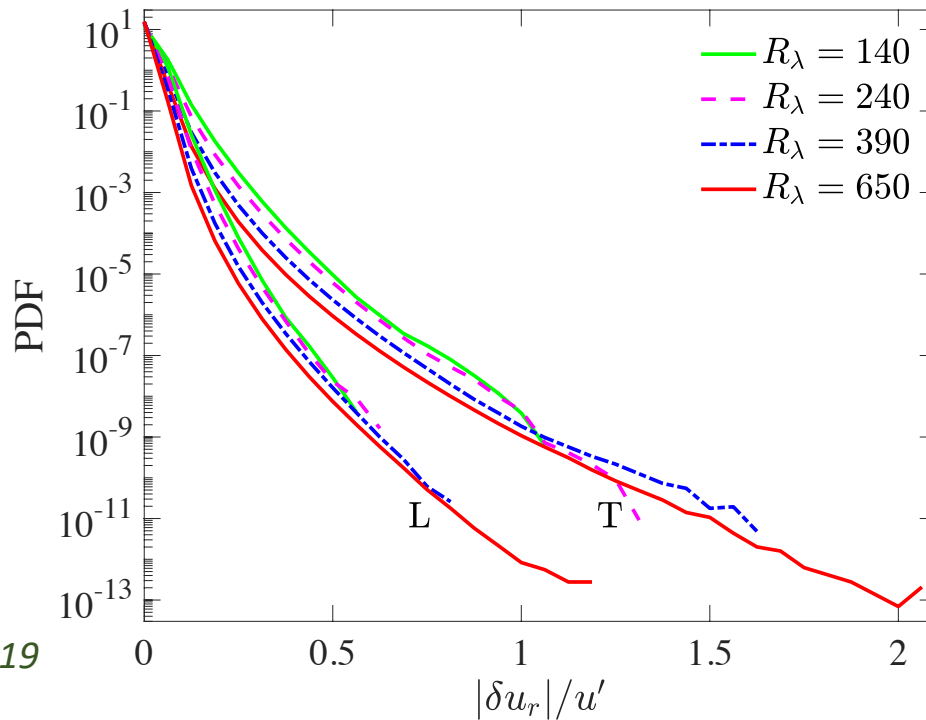
- The distribution of $\Omega/\langle\Omega\rangle$ become wider when R_λ increases.
- Same conclusion Σ , defined as $\Sigma = 2 \text{tr}(S^2)$;
- the fluctuations of $\Sigma/\langle\Sigma\rangle$ are slightly smaller than those of $\Omega/\langle\Omega\rangle$.

Velocity differences at scales $\leq \eta$.

- **Observation:**

Velocity differences δu_r can be as large as u' , the r.m.s. velocity (Jimenez et al, 1993).

If anything, the velocity diff. at $\eta/2$ (and also η) grows when Re_λ increases.



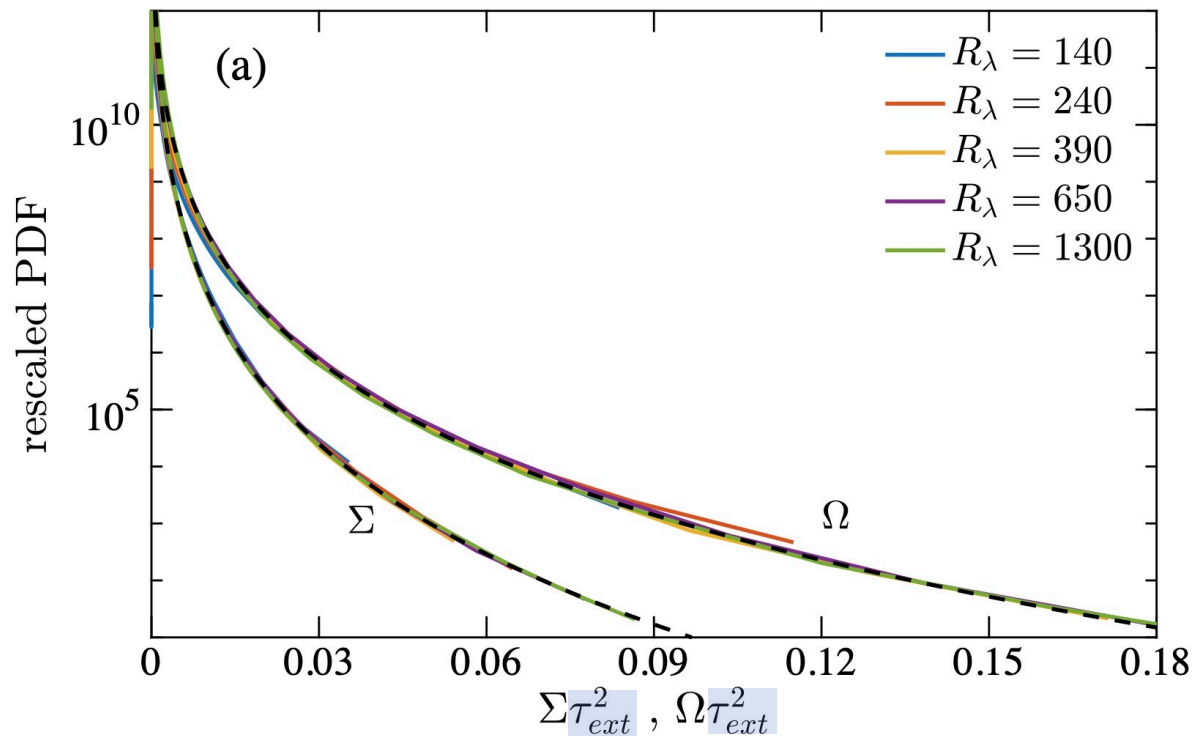
$$r = \eta/2.$$

T : transverse velocity differences;

L : longitudinal velocity diff.

Two main numerical observations.

Observation 1: Scaling of the large gradients with Re_λ .



Main result:

PDF of $\Omega \tau_K^2$ and $\Sigma \tau_K^2$ show tails that rapidly grow when Re_λ increases.

The tails of these PDFs can be very well collapsed by rescaling with $Re_\lambda^{2\beta}$ -- which means that the largest fluctuations of vorticity and strain scale in fact like:

$$\omega, S \propto 1/\tau_{ext} = Re_\lambda^\beta / \tau_K$$

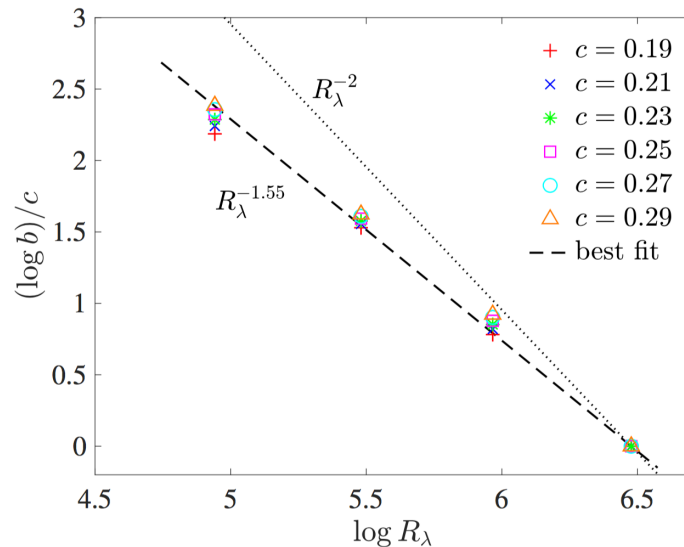
$$\tau_{ext} \sim \tau_K Re_\lambda^{-\beta}$$

Definitions: $\Omega = \omega^2$; $\Sigma = 2 \text{tr}(S^2)$.

Buaria et al, PRL 2022

Scaling of the PDF: a systematic approach

- Observe that the distribution can be well fitted by stretched exponential functional form: $P(x) = a \exp(-b x^c)$ where the exponent $c \sim 1/4$.
- Fit the data with a given value of the exponent c around $1/4$, and look for the dependence of b as a function of R_λ :

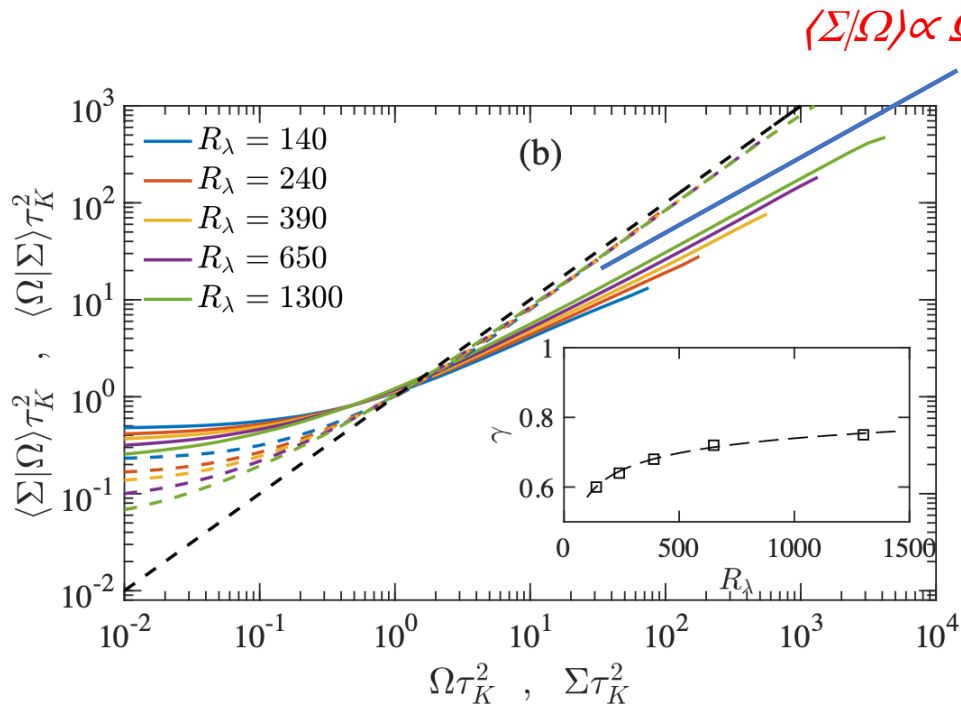


Conclusion:

Values of $b^{1/c}$ are consistent with the observed collapse of the PDFs.

Observation 2: Strain acting on large vorticity.

- Question: What is the strain for a vortex with a very large vorticity?



Answer:

the strain Σ ($= 2 \text{ tr}(S^2)$), conditioned on Ω ($= \omega^2$) grows as $\langle \Sigma / \Omega \rangle \propto \Omega^\gamma$;

Exponent: γ is a function of R_λ (see inset).

$$(1 - \gamma) = p R_\lambda^{-q}, \quad p, q > 0$$

$$\log p = -0.033 \text{ and } q = 0.189.$$

Interpretation

Size of a strained vortex.

- The size of a vortex tube results from a balance between viscosity and strain (think of a Burgers vortex):

$$\eta_{Burgers} \sim \text{radius} \sim (v/S_{out})^{1/2}$$

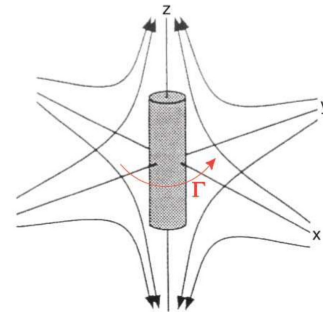
- A guess for the strain acting on an intense vortex of intensity Ω :

$$\langle \Sigma / \Omega \rangle \tau_K^2 \propto (\Omega \tau_K^2)^\gamma$$

=> suggests that the size $R(\Omega)$ of an intense vortex, of intensity Ω , is:

$$R(\Omega) = (v^2 / \langle \Sigma / \Omega \rangle)^{1/4} \sim \eta_K (\tau_K^2 \Omega)^{-\gamma/4}$$

S_{out} =
straining rate



Hamlington *et al.*,
PRE 2008

Buaria *et al.*, PRR
2021.

Connection with the observed scalings.

The velocity difference across very intense tubes is $\sim u'$:

$$\Omega \sim u'^2 / R(\Omega)^2$$

Solve:

$$\Omega \tau_K^2 \propto Re_\lambda^{2/(2-\gamma)}$$

+ identify with earlier definitions:

$$\beta = 1/(2-\gamma).$$

- This agrees quantitatively with our own numerical values !

Corresponding smallest scale: $u' / \eta_{ext} \sim \tau_{ext}$

=>

$$\eta_{ext} \sim \eta_K Re_\lambda^{-\alpha}; \quad \alpha = \beta - 1/2 = \gamma / [2(2-\gamma)]$$

See Buaria et al, NJP 2019
and PRL 2022.

R_λ -dependence: implications for the fits of the PDFs

- Postulate that the tails of the PDF behave as: $f_X(x) \approx a \exp(-bx^c)$,
(empirically, c is a fixed number $\sim 1/4$).

- Superposition of the PDFs by rescaling x by $(x R_\lambda^\beta)$: $b^{1/c} \sim R_\lambda^{-2\beta}$

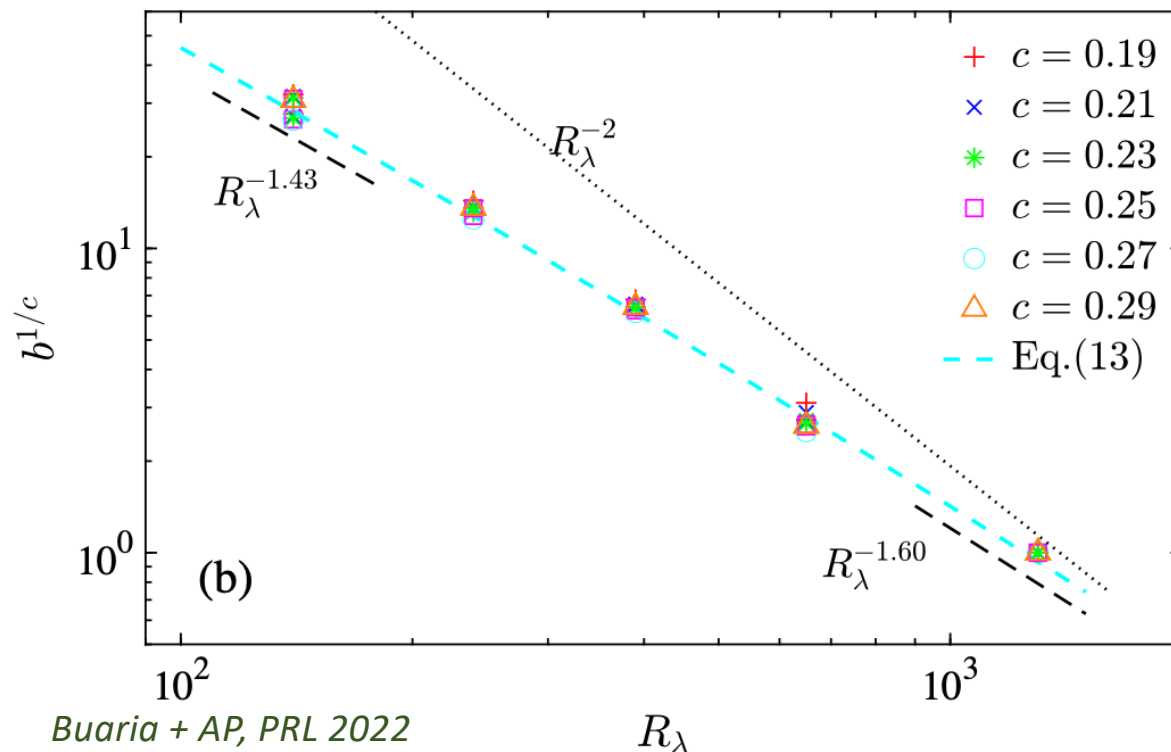
- write the relation above as an ODE:

$$d \ln(b^{1/c}) / d \ln(R_\lambda) = -2\beta$$

- Use: $\beta = 1/(2-\gamma)$ with $\gamma = 1-p R_\lambda^{-q}$

- Solve (...calculate an integral...).

R_λ -dependence of the PDFs



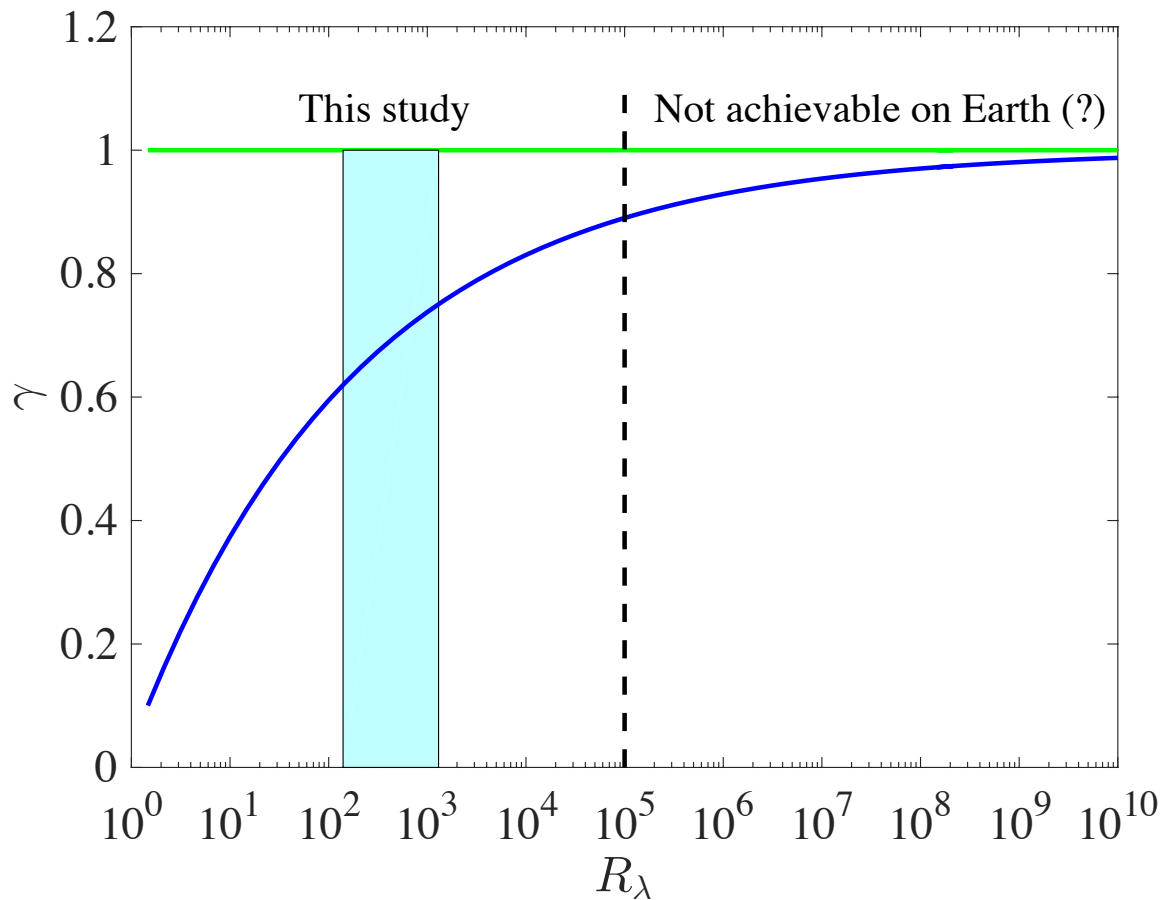
Dashed line: result of the calculation
With the functional fit for γ :

$$\ln(b^{1/c}) = -2 \ln(R_\lambda) - \left(\frac{2}{0.189}\right) \ln\left[1 + \exp(-0.033 - 0.189 \ln(R_\lambda))\right]$$



Dependence of β on R_λ : plausibly (?) $\beta \rightarrow 1$ when $R_\lambda \rightarrow \infty$

How close can one get to the R_λ infinity asymptotic regime ?



IF the fit proposed for γ holds...

... then, the $R_\lambda \rightarrow \infty$ regime (say $\gamma > 0.99$) is unreachable on Earth !

Analysis of strain:
local and nonlocal aspects and
implications for the regularity of Navier-
Stokes

Nonlocal relation between strain and vorticity

Relation between strain and vorticity is nonlocal (\sim Biot-Savart relation) !

$$S_{ij}(\mathbf{x}) = PV \int_{\mathbf{x}'} \frac{3}{8\pi} (\epsilon_{ikl} r_j + \epsilon_{jkl} r_i) \omega_l(\mathbf{x}') \frac{r_k}{r^5} d^3 \mathbf{x}'$$
$$\mathbf{r} = \mathbf{x} - \mathbf{x}'$$

Here: separate the *local (L)* and *nonlocal (NL)* contributions to strain:

$$S_{ij}(\mathbf{x}) = \underbrace{\int_{r>R} [\dots] d^3 \mathbf{x}'}_{=S_{ij}^{NL}(\mathbf{x},R)} + \underbrace{\int_{r\leq R} [\dots] d^3 \mathbf{x}'}_{=S_{ij}^L(\mathbf{x},R)}$$

Decomposition: practical aspects

Performing the Biot-Savart directly is prohibitively costly from a numerical point of view !

An other approach: use the expansion ([Hamlington, PRE 2008](#))

$$S_{ij}^{\text{NL}}(\mathbf{x}, R) = \left[1 + \frac{R^2}{10} \nabla^2 + \frac{R^4}{280} \nabla^2 \nabla^2 + \dots \right. \\ \left. + \frac{3R^{2n-2}}{(2n-2)!(4n^2-1)} (\nabla^2)^{n-1} + \dots \right] S_{ij}(\mathbf{x}) .$$

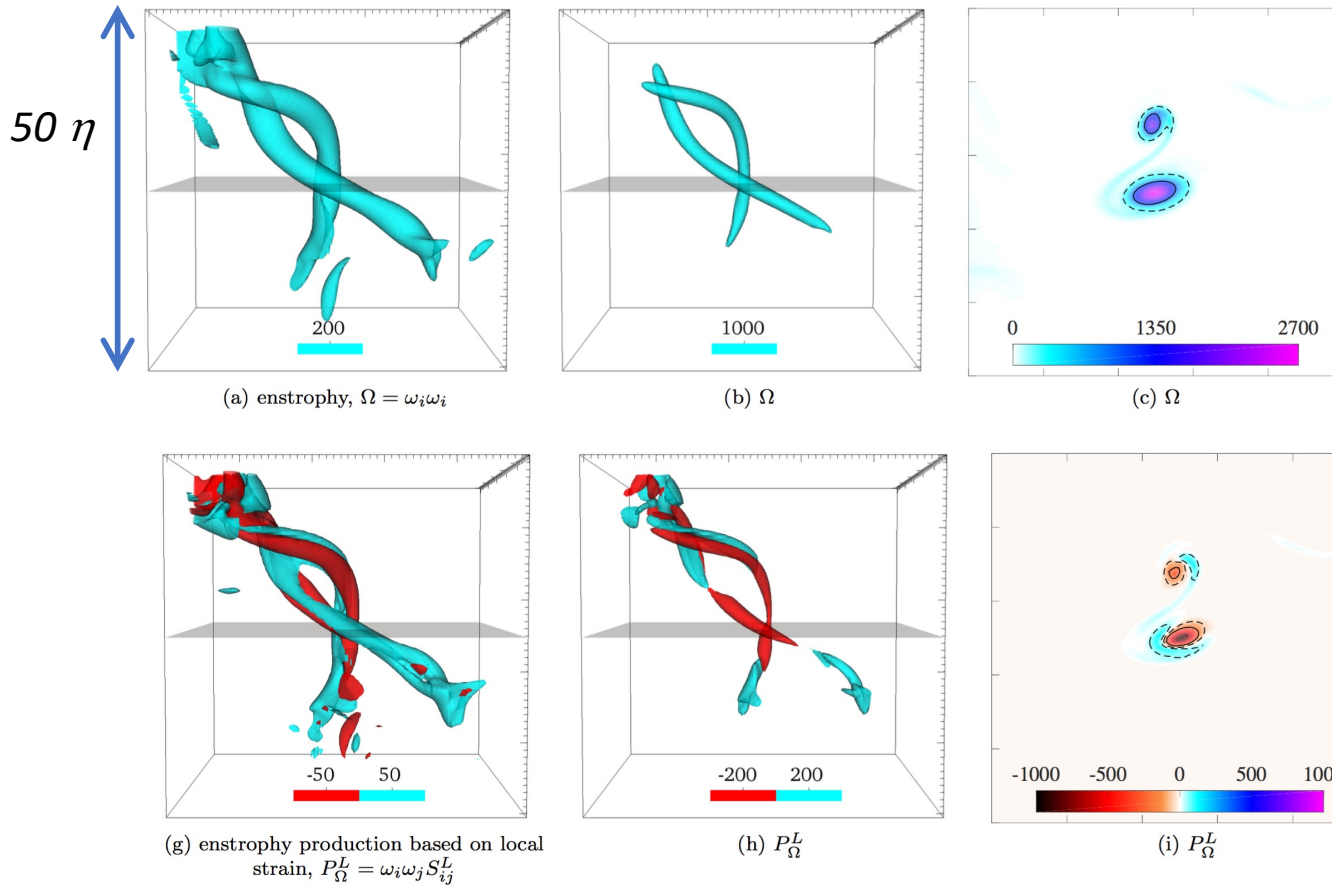
In Fourier space, this can be re-expressed ([Buaria et al, Nat Comm. 2020](#)):

$$\hat{S}_{ij}^{\text{NL}}(\mathbf{k}, R) = f(kR) \hat{S}_{ij}(\mathbf{k}) \quad f(kR) = \frac{3 [\sin(kR) - kR \cos(kR)]}{(kR)^3}$$

⇒ Efficient way to compute of S^{NL} ; practical from a numerical point of view.

⇒ Our results agree with the available data from Hamlington *et al.* (Phys. Fluids, 2008).

How much local (self-) amplification for extreme events ?



Upper row: Enstrophy ($\Omega = \omega^2$)

Lower row: Amplification term:

$$P_{\Omega}^L = \omega \cdot S^L \cdot \omega$$

with $R = 2 \eta$.

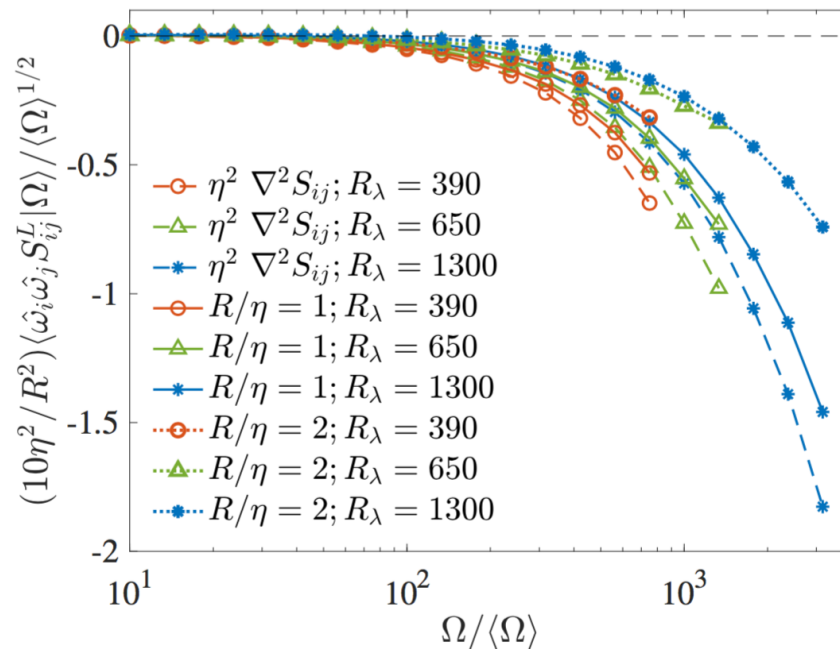
Main observation:

P_{Ω}^L is negative when Ω is large.

Buaria et al, Nat. Comm., 2020

How much local (self-) amplification for extreme events ?

Statistical analysis: compute the conditional average of the production term.



n.b.: It turns out that the production term,

$$P^L_{\Omega} = \omega \cdot S^L \cdot \omega$$

is *almost always negative* when

$$R \lesssim 2 \eta$$

=> self-attenuation of vorticity.

Self-attenuation and “helicity”

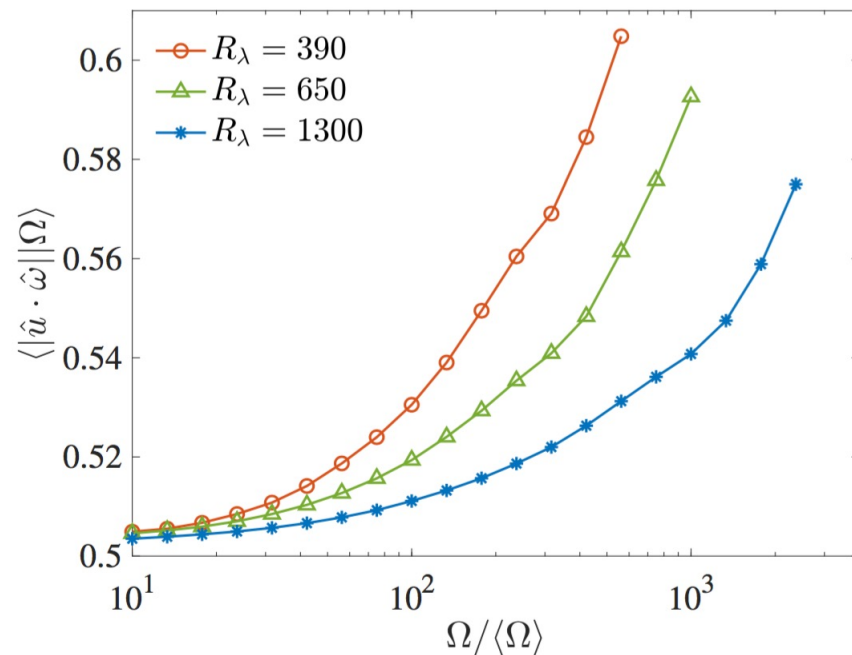


FIG. 3. **Preferential alignment of vorticity and velocity in regions of intense vorticity.** Averaged absolute value of the cosine between velocity and vorticity vectors, conditioned on enstrophy relative to its mean value, at Taylor-scale Reynolds numbers $R_\lambda = 390 - 1300$.

Analysis of the flow (...)

=>

there must be some alignment between vorticity and velocity in the most intense vortex structures, as observed numerically

(also noticed by Choi et al, PRE 2009).

Lessons for Navier-Stokes regularity

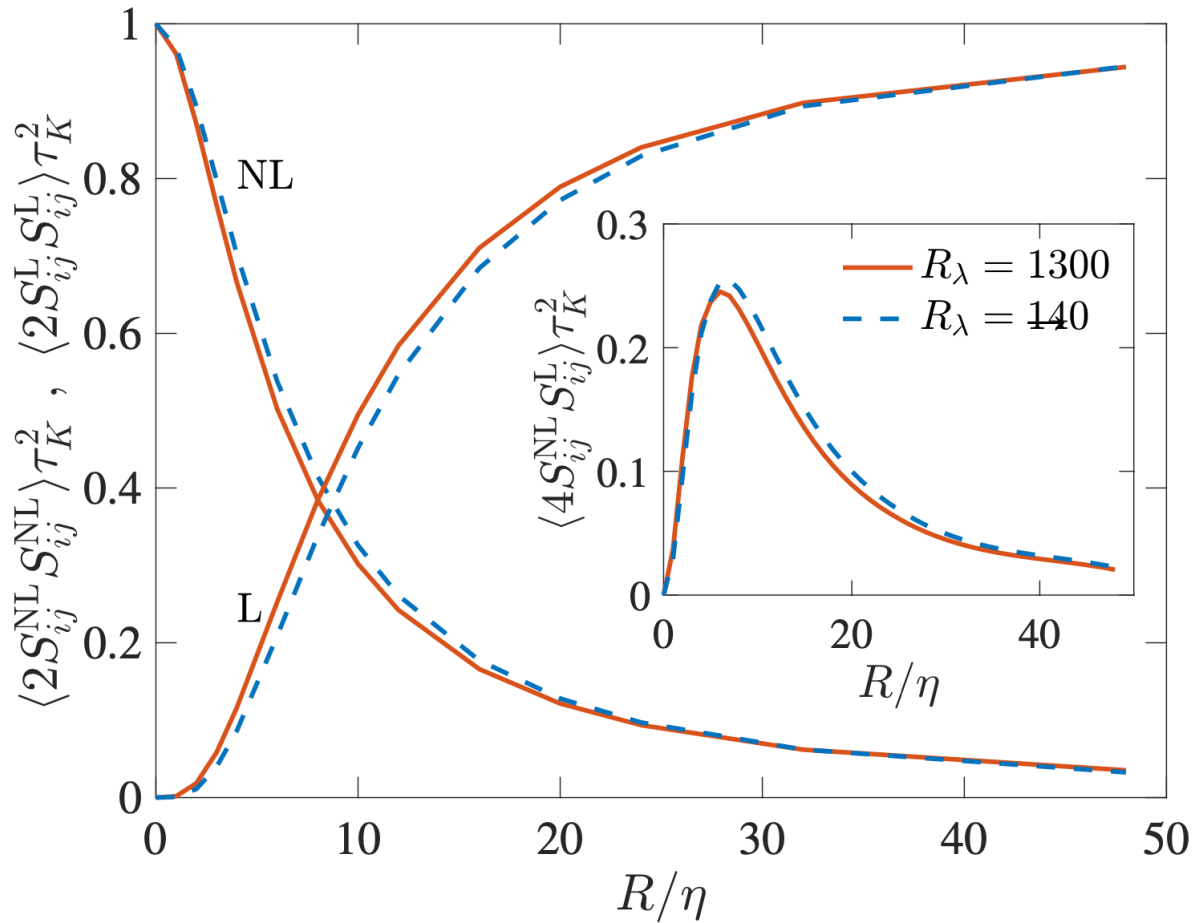
- *Lesson learned*: in DNS, no self-amplification of the most intense vortex structures. On the contrary, “self-interaction” leads to a weakening of the vortex.

=> the very intense events cannot be infinitely strong.

- Understanding the physical origin of the effect, and generalizing the numerical results to “any flow” would be sufficient to show regularity of the Navier-Stokes equations ([Constantin et al. Comm PDE, 1996](#)).

*Decomposition of strain:
implications for the regions of intense velocity
gradient.*

Local vs. nonlocal strain



Obvious remarks:

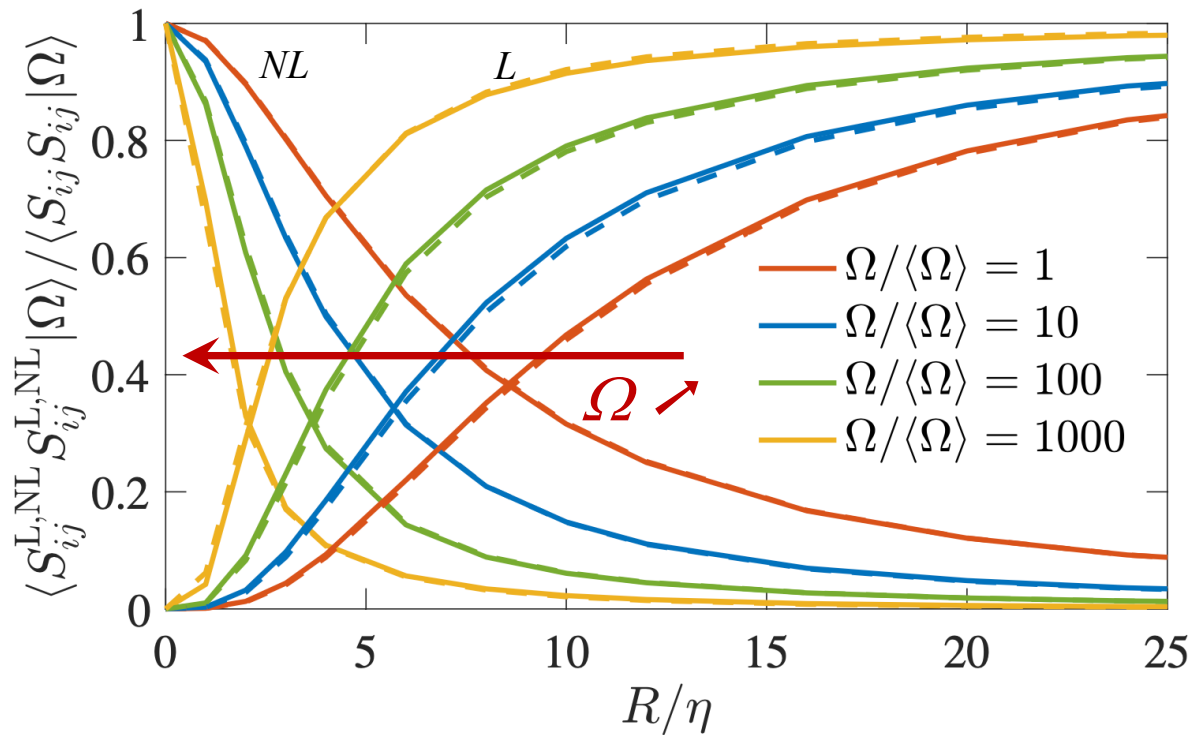
- when $R/\eta \rightarrow 0$, $S^{NL} \sim S$, $S^L \sim 0$
- when $R/\eta \rightarrow \infty$, $S^{NL} \sim 0$, $S^L \sim S$

\Rightarrow there exists a scale ρ , at which the two are comparable:

$$\rho \sim 10 \eta$$

nb: this scale does not depend very much on R_λ .

Local vs. nonlocal strain: conditioning on vorticity



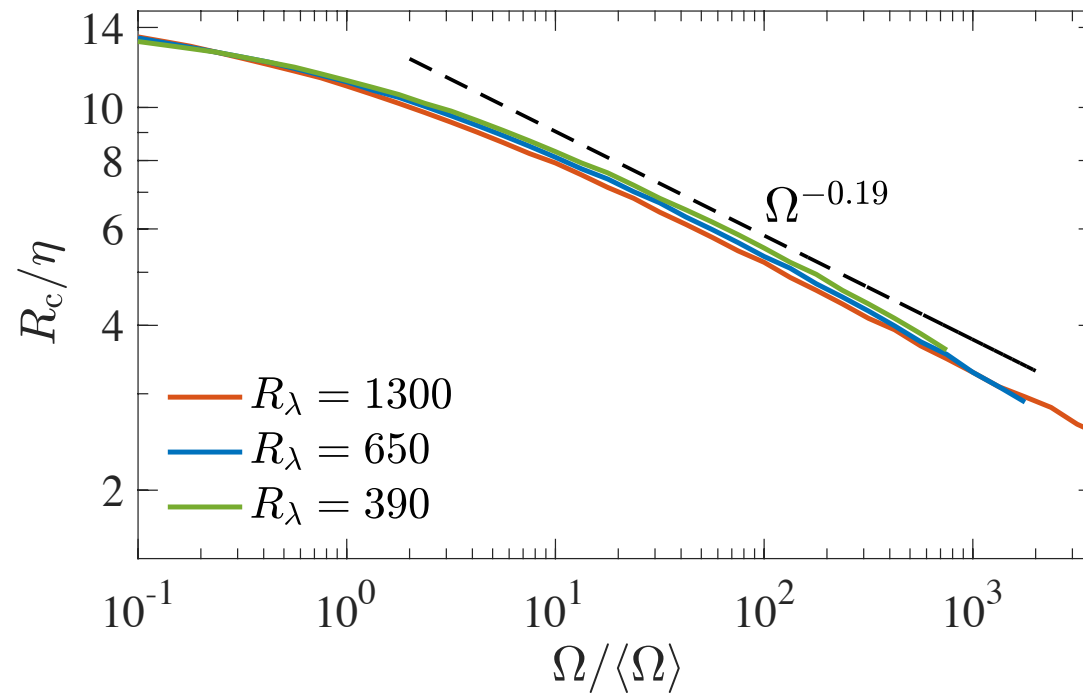
Full lines: $R_\lambda = 1,300$;
Dashed lines: $R_\lambda = 650$.

Condition on the intensity of vorticity, Ω .

\Rightarrow When Ω increases, the size $\rho(\Omega)$ at which $|S^{NL}| \sim |S^L|$ decreases.

Dependence of ρ on Ω ?

Dependence of the size on Ω



Plausible scaling of $\rho(\Omega)$:

$$\rho(\Omega) \sim \Omega^{-\gamma/4}.$$

... as expected based on the phenomenological argument



Is there some underlying “self-similarity” ?

With what we know, the answer appears to be negative.

For the most extreme events, the stretching induced by the local contribution of strain changes sign:

$$(\omega \cdot S^L \cdot \omega) \text{ becomes } < 0 \text{ for } \Omega \gtrsim 100.$$

~ The local strain opposes further growth of vorticity when Ω *reaches extreme values* (Buaria et al, Nat. Comm. 2020).

=> This effectively breaks the self-similarity (in Ω).

Conclusions

- The very large fluctuations of the velocity gradients behave as R_λ^β / τ_K , with

$\beta = 0.775 \pm 0.025$ over the range of Reynolds number considered ($140 \leq R_\lambda \leq 650$).

- The largest gradients consist of vortex tubes, with a velocity jump $\sim u_{rms}$; over a distance $\sim \eta_K R_\lambda^\alpha$, with $\alpha = \beta - 1/2$.
- Relation with the straining rate $\langle S^2 / \Omega^2 \rangle \propto \Omega^\gamma$; with $\beta = 1/(2-\gamma)$.
- Characteristic size of the vortices seems to emerge: $\rho(\Omega) \sim \Omega^{-\gamma/4}$.

... but only approximate self-similarity ...

\sim Slow variation of γ , hence β . *What is the $R_\lambda \rightarrow \infty$ limit ??*

Thanks for your attention!

Questions ?

Supercomputing resources:

[GCS/JSC](#) (Jukeen/Juwels), [XSEDE](#) (Stampede2/Frontera)

- Talk based on the following references:
- D. Buaria, A. Pumir, E. Bodenschatz and P.K. Yeung, *New J Phys* **21**, 043004 (2019)
- D. Buaria, A. Pumir and E. Bodenschatz, *Nat. Comm.* **11**, 5852 (2020)
- D. Buaria and A. Pumir, *Phys. Rev. Res.* **3**, L042020 (2021)
- D. Buaria and A. Pumir, *Phys. Rev. Lett.* **128**, 094501 (2022)
- D. Buaria, A. Pumir and E. Bodenschatz, *Phil. Trans. A* **380**, 20210088 (2022).
- D. Buaria and A. Pumir, in preparation (2023).